

# LINEAR DIFFERENTIAL EQUATIONS OVER ARBITRARY ALGEBRAICALLY CLOSED FIELDS

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ABSTRACT. Let  $K$  be an arbitrary algebraically closed field of characteristic zero and let  $K[[x]]$  be the ring of integral formal power series; let  $\Omega$  be the  $K$ -subalgebra of  $K[[x]]$  generated by  $x$  and the subset  $T_K = \{\exp(\lambda x) : \lambda \in K\}$ . In this note we supply some easy and elegant proofs for some classical results on the preimage of elements of the form  $x^q Q(x) \exp(rx)$  through a linear differential operator with coefficients in  $K$ . We also make some theoretical considerations on the structure of the space of all solutions for a linear ODE defined over  $K[[x]]$ .

## 1. SOME INTRODUCTORY REMARKS

Let  $K$  be an algebraically closed field of characteristic zero [LS] and let  $x$  be a variable over  $K$  (simply an element  $x$  not belonging to  $K$ ). Let  $K[[x]]$  be the ring of all formal integral power series  $f = a_0 + a_1x + \dots$ ,  $a_i \in K$ ,  $i = 0, 1, \dots$ . Here  $\frac{d}{dx} : K[[x]] \rightarrow K[[x]]$ ,  $\frac{df}{dx} = a_1 + 2a_2x + \dots + na_nx^{n-1} + \dots$ , is the usual differential operator defined on  $K[[x]]$ . For  $y \in K[[x]]$ , we also denote

$$y^{(n)} = \frac{d^n y}{dx^n} = \left( \underbrace{\frac{d}{dx} \circ \dots \circ \frac{d}{dx}}_{n\text{-times}} \right) (y).$$

**Theorem 1.** *Let  $b_1, \dots, b_n, c$  be  $n + 1$  elements in  $K[[x]]$ . Then any solution  $y \in K[[x]]$  of the linear differential equation*

$$(1.1) \quad y^{(n)} + b_1 y^{(n-1)} + \dots + b_n y = c,$$

*is of the form:*

$$(1.2) \quad y = d_0 + d_1 x + \dots + d_t x^t + \dots,$$

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where  $d_0, \dots, d_{n-1}$  are  $n$  free parameters in  $K$  and

$$(1.3) \quad d_{n+k} = \sum_{j=0}^k \alpha_j^{(k)} c_j + \sum_{i=0}^{n-1} \beta_i^{(k)} d_i,$$

$k = 0, 1, \dots$ ,  $\alpha_j^{(k)}, \beta_i^{(k)} \in \mathbb{Q}[b_{uv}]$ , where

$$(1.4) \quad b_u = b_{u0} + b_{u1}x + \dots,$$

$$(1.5) \quad c = c_0 + c_1x + \dots,$$

$b_{uv}, c_j \in K$ ,  $u = 1, 2, \dots, n$ ,  $v = 0, 1, \dots$ .

*Proof.* For  $y$  of the form (1.2) one has:

$$(1.6) \quad y^{(m)} = \sum_{t=m}^{\infty} t(t-1)\dots(t-m+1) d_t x^{t-m},$$

$m = 1, 2, \dots, m$ . Let us prove (1.3) by mathematical induction. In order to prove (1.3) for  $k = 0$ , we consider the equality (1.1) modulo  $x$ , i.e. we look at it in the quotient ring  $K[[x]]/(x)$ , where  $(x)$  is the ideal generated by  $x$  in  $K[[x]]$ . Thus we get:

$$(1.7) \quad n!d_n + b_{10}(n-1)!d_{n-1} + \dots + b_{n0}d_0 = c_0.$$

Since the characteristic of  $K$  is equal to 0 ( $\mathbb{Q} \subset K$ ), we obtain:

$$d_n = \alpha_0^{(0)} c_0 + \sum_{i=0}^{n-1} \beta_i^{(0)} d_i,$$

where  $\alpha_0^{(0)} = \frac{1}{n!}$ ,  $\beta_i^{(0)} = -\frac{i!}{n!} b_{n-i,0} d_i$ ,  $i = 0, 1, \dots, n-1$ . We assume now that formula (1.3) is true for  $k = 0, 1, \dots, q$ . Let us prove it for  $k = q+1$ . For this, we come back to (1.1) and consider it modulo  $x^{q+2}$ :

$$(1.8) \quad \sum_{t=n}^{n+q+1} \frac{t!}{(t-n)!} d_t x^{t-n} + \left[ \sum_{l=0}^{q+1} b_{1l} x^l \right] \left[ \sum_{t=n-1}^{n+q} \frac{t!}{(t-n+1)!} d_t x^{t-n+1} \right] +$$

$$+ \dots + \left[ \sum_{l=0}^{q+1} b_{nl} x^l \right] \left[ \sum_{t=0}^{q+1} d_t x^t \right] = c_0 + c_1 x + \dots + c_{q+1} x^{q+1}$$

In this last polynomial equality we identify the coefficients of  $x^{q+1}$  and get:

$$\frac{(n+q+1)!}{(q+1)!} d_{n+q+1} + \sum_{l=0}^{q+1} \frac{(n+q-l)!}{(q-l+1)!} b_{1l} d_{n+q-l} + \dots +$$

$$(1.9) \quad + \sum_{l=0}^{q+1} b_{nl} d_{q+1-l} = c_{q+1}.$$

Since in these above sums appear (excepting the constants!) only  $d_0, \dots, d_n, \dots, d_{n+q}$  and since  $d_n, d_{n+1}, \dots, d_{n+q}$  are computed by using formulas (1.3) - mathematical induction hypotheses - we finally conclude that  $d_{n+q+1}$  can be written as in (1.3). If  $c = 0$ , i.e.  $c_0 = c_1 = \dots = 0$ , we see from (1.3) that  $d_{n+k}$  are linear combinations of  $d_0, \dots, d_{n-1}$ , i.e. the vector space of all solutions of the homogenous equation (1.1) (with  $c = 0$ ) is exactly equal to  $n$ .  $\square$

**Remark 1.** If, in (1.1),  $c = 0$ , i.e.  $c_0 = c_1 = \dots = 0$ , we see from (1.3) that  $d_{n+k}$  are linear combinations of  $d_0, \dots, d_{n-1}$ , i.e. the vector space of all solutions of the homogenous equation (1.1) (with  $c = 0$ ) is exactly equal to  $n$ .

**Remark 2.** Theorem 1 can be viewed as an existence and uniqueness theorem for the following Cauchy problem in  $K[[x]]$ : find  $y = y(x) \in K[[x]]$  such that the equality (1.1) is true and  $y(0) = d_0$ ,  $y'(0) = d_1, \dots, y^{(n-1)}(0) = (n-1)!d_{n-1}$  are given. This means to fix  $d_0, \dots, d_{n-1}$  in (1.2). Since  $d_n, d_{n+1}, \dots$  are linear functions of  $d_0, \dots, d_{n-1}, c_0, c_1, \dots$  (see (1.3)), the existence and uniqueness of  $y$  is clear enough. Here, for  $f \in K[[x]]$ ,  $f(0)$  means the constant term of  $f$ .

For any element  $\lambda \in K$  we denote  $\exp(\lambda x)$  the following formal power series:

$$(1.10) \quad \exp(\lambda x) = \sum_{n=0}^{\infty} \frac{\lambda^n}{n!} x^n$$

with coefficients in  $K$ . Since  $\mathbb{Q} \subset K$ , one can easily see that

$$\exp(\lambda x) \cdot \exp(\mu x) = \exp((\lambda + \mu)x),$$

for any  $\lambda, \mu \in K$ .

Let us denote  $T_K = \{\exp(\lambda x) : \lambda \in K\}$  and let  $\Omega$  be the  $K$ -subalgebra of  $K[[x]]$  generated by the variable  $x$  and by the subset  $T_K$ . In the following we shall consider linear differential equations of the form (1.1), with  $c = 0$  and  $b_1, \dots, b_n$  constant elements, i.e. elements in  $K$ .

Let  $I$  be the identity operator defined on  $\Omega$  and let  $L : \Omega \rightarrow \Omega$  be the following linear differential operator:

$$(1.11) \quad L[y] = y^{(n)} + a_1 y^{(n-1)} + \dots + a_{n-1} y' + a_n y,$$

where  $y \in \Omega$ ,  $y^{(j)} = \frac{d^j y}{dx^j}$  and  $a_j \in K$  for any  $j = 1, 2, \dots, n$ . Here  $\frac{d^0}{dx^0} = I$ .

The equation

$$(1.12) \quad E(z) = z^n + a_1 z^{n-1} + \dots + a_{n-1} z + a_n = 0$$

is called the associated algebraic equation to the differential operator  $L$ . Let  $r_1, r_2, \dots, r_n \in K$  be all the roots of equation (1.12). After an eventually appropriate rearrangement of  $r_1, r_2, \dots, r_n$ , let  $r_1, r_2, \dots, r_k, k \leq n$ , be all the distinct roots with their algebraic multiplicities  $t_1, t_2, \dots, t_k$  respectively. So

$$(1.13) \quad E(z) = (z - r_1)^{t_1} (z - r_2)^{t_2} \dots (z - r_k)^{t_k}$$

is the decomposition of the polynomial  $E(z)$  in coprime factors over the algebraically closed field  $K$ . The decomposition (1.13) induces the following decomposition of the linear operator  $L$  into powers of linear differential operators of order one:

$$(1.14) \quad L = \left( \frac{d}{dx} - r_1 I \right)^{t_1} \left( \frac{d}{dx} - r_2 I \right)^{t_2} \dots \left( \frac{d}{dx} - r_k I \right)^{t_k}$$

In this note we supply new easy elementary proofs (they can be used even in the undergraduate teaching!) for the following classical results (known for  $K = \mathbb{C}$ , the field of complex numbers).

**Theorem 2.** *Let  $\lambda \in K \setminus \{r_1, r_2, \dots, r_k\}$  and let  $Q \in K[x]$ ,  $\deg Q = m$  be an arbitrary polynomial of degree  $m$  with coefficients in the field  $K$ . Then there exists a unique polynomial  $P \in K[x]$  of degree  $m$  such that*

$$(1.15) \quad L[P \exp(\lambda x)] = Q \exp(\lambda x).$$

**Theorem 3.** *Let  $q$  be a natural number (0 included) and let  $Q \in K[x]$  be a polynomial of degree  $m$ . Then there exists a unique polynomial  $P_q \in K[x]$  of degree  $m$  such that*

$$(1.16) \quad L[x^{q+t_1} P_q \exp(r_1 x)] = x^q Q \exp(r_1 x),$$

where  $r_1$  is a root of algebraic multiplicity  $t_1$  of the above equation (1.12). In particular, if  $q = 0$ , we get a classical result in LDE of order  $n$  with constant coefficients.

## 2. PROOF OF THEOREMS 2, 3 AND SOME OTHER REMARKS

**Lemma 1.** *Let  $\lambda, r \in K$ ,  $\lambda \neq r$  and let  $Q \in K[x]$  be a polynomial of degree  $m$  with coefficients in  $K$ . Then there exists a unique polynomial  $P \in K[x]$  of degree  $m$  such that*

$$(2.1) \quad \left( \frac{d}{dx} - r I \right) [P \exp(\lambda x)] = Q \exp(\lambda x).$$

If  $K_0$  is a subfield of  $K$ , if  $\lambda, r \in K_0$  and if  $Q \in K_0[x]$ , then this polynomial  $P$  has coefficients in  $K_0$ .

*Proof.* Let us compute the left side of (2.1) and then simplify by  $\exp(\lambda x)$ . We get:

$$(2.2) \quad P' + (\lambda - r)P = Q.$$

If we write  $Q(x) = c_0 + c_1x + \dots + c_mx^m$ , from (2.2) one can easily uniquely determine the coefficients  $b_0, b_1, \dots, b_m$  of the searched for polynomial  $P(x) = b_0 + b_1x + \dots + b_mx^m$ . Moreover, we see that each  $b_j$  is a linear expression of  $c_0, c_1, \dots, c_m$  with coefficients in  $\mathbb{Q}(\lambda, r)$  which is included in any subfield  $K_0$  of  $K$  with  $\lambda, r \in K_0$ . Here  $\mathbb{Q}$  is the subfield of rational numbers viewed in  $K$  (since the characteristic of  $K$  is equal to zero).  $\square$

**Lemma 2.** Let  $r \in K$ ,  $Q \in K[x]$ ,  $\deg Q = m$  and  $q \in \mathbb{N}$ . Then there exists a unique polynomial  $P_q \in K[x]$ ,  $\deg P_q = m$ , such that:

$$(2.3) \quad \left( \frac{d}{dx} - rI \right) [x^{q+1}P_q \exp(rx)] = x^q Q \exp(rx).$$

If  $r \in K_0$ , a subfield of  $K$ , and  $Q \in K_0[x]$ , the  $P_q \in K_0[x]$ .

*Proof.* Computing the left side of (2.3) and then simplifying by  $x^q \exp(rx)$ , one obtains:

$$(2.4) \quad (q+1)P_q + xP_q' = Q.$$

If we write again  $Q(x) = c_0 + c_1x + \dots + c_mx^m$ , it is easy to uniquely determine the coefficients  $d_0, d_1, \dots, d_m$  of the searched polynomial  $P_q(x) = d_0 + d_1x + \dots + d_mx^m$  as linear combinations of  $c_0, c_1, \dots, c_m$  with coefficients in  $\mathbb{Q}(r)$  which is included in any subfield of  $K$  which contains  $r$ .  $\square$

Now we can prove Theorem 2.

*Proof.* (Theorem 2) Mathematical Induction is used on  $n = t_1 + t_2 + \dots + t_k$  (see the above notation). For  $n = k = t_1 = 1$ , one directly apply Lemma 1. Assume that the statement of Theorem 2 is true for  $h = 1, 2, \dots, n-1$ . Let us prove it for  $h = n$ . Let

$$L = \left( \frac{d}{dx} - r_1I \right) L^*,$$

where

$$(2.5) \quad L^* = \left( \frac{d}{dx} - r_1I \right)^{t_1-1} \left( \frac{d}{dx} - r_2I \right)^{t_2} \dots \left( \frac{d}{dx} - r_kI \right)^{t_k}.$$

Let  $P_1 \in K[x]$  be the unique polynomial of degree  $m$  with

$$(2.6) \quad \left( \frac{d}{dx} - r_1 I \right) [P_1 \exp(\lambda x)] = Q \exp(\lambda x).$$

(see Lemma 1). Let now  $P \in K[x]$  be the unique polynomial of degree  $m$  such that

$$(2.7) \quad L^* [P \exp(\lambda x)] = P_1 \exp(\lambda x).$$

(see the above Mathematical Induction assumption).

Apply now  $\left( \frac{d}{dx} - r_1 I \right)$  in both sides in (2.7) and finally obtain

$$L[P \exp(\lambda x)] = Q \exp(\lambda x),$$

i.e. the statement of Theorem 2. □

Let now prove Theorem 3.

*Proof.* (Theorem 3) The same Mathematical Induction on  $n = t_1 + t_2 + \dots + t_k$  is used. For  $n = k = t_1 = 1$ , one can simply apply Lemma 2. Suppose that the statement of Theorem 3 is true for  $h = 1, 2, \dots, n - 1$ . Let us prove it for  $h = n$ . Let again

$$L = \left( \frac{d}{dx} - r_1 I \right) L^*,$$

where  $L^*$  is defined in (2.5). Let  $P_{1,q} \in K[x]$  be the unique polynomial of degree  $m$  with

$$\left( \frac{d}{dx} - r_1 I \right) [x^{q+1} P_{1,q} \exp(r_1 x)] = x^q Q \exp(r_1 x).$$

(see Lemma 2).

Let now  $P \in K[x]$  be the unique polynomial of degree  $m$  with

$$(2.8) \quad L^* [x^{q+1+t_1-1} P_q \exp(r_1 x)] = x^{q+1} P_{1,q} \exp(r_1 x).$$

Let us apply  $\left( \frac{d}{dx} - r_1 I \right)$  both sides in (2.8). Finally we get that  $P_q$  is the unique required polynomial in (1.16) and the proof of Theorem 3 is complete. □

Let us say some words on the "structure of solutions" of the equation  $L[y] = 0$  in this general frame.

**Lemma 3.** *Let  $r_1$  be a root of algebraic multiplicity  $t_1$  of the polynomial equation  $E(z) = 0$  (see 1.12). Then for any polynomial  $P(x) \in K[x]$  with  $\deg P < t_1$  one has that  $L[P \exp(r_1 x)] = 0$ .*

*Proof.* We simply successively compute

$$\begin{aligned} \left(\frac{d}{dx} - r_1 I\right) [P(x) \exp(r_1 x)] &= P'(x) \exp(r_1 x), \\ \left(\frac{d}{dx} - r_1 I\right)^2 [P(x) \exp(r_1 x)] &= \left(\frac{d}{dx} - r_1 I\right) [P'(x) \exp(r_1 x)] = \\ &= P''(x) \exp(r_1 x), \dots \\ \dots \left(\frac{d}{dx} - r_1 I\right)^{t_1} [P(x) \exp(r_1 x)] &= P^{(t_1)}(x) \exp(r_1 x) = 0, \end{aligned}$$

because the  $t_1$ -th derivative of a polynomial of degree less than  $t_1$  is equal to zero.  $\square$

**Lemma 4.** *Let  $r_1, r_2, \dots, r_k$  be  $k$  distinct elements in  $K$ . Then  $\exp(r_1 x), \exp(r_2 x), \dots, \exp(r_k x)$  are (as elements in the vector space  $\Omega$  over  $K(x)$ ) linear independent over  $K(x)$ . Here  $K(x)$  is the rational function field in the variable  $x$  over the initial field  $K$ .*

*Proof.* Let

$$(2.9) \quad P_1(x) \exp(r_1 x) + P_2(x) \exp(r_2 x) + \dots + P_k(x) \exp(r_k x) = 0,$$

where we can assume that  $P_1(x), P_2(x), \dots, P_k(x)$  are nonzero polynomials of degrees  $n_1, n_2, \dots, n_k$  respectively. We want to prove that all these polynomials are zero. Let  $n = n_1 + n_2 + \dots + n_k$  be the sum of all degrees of these polynomials. Since we just assumed that all polynomials are nonzero, we have that  $n \geq 0$ . From the set of all linear combinations like in (2.9) we choose one with  $n$  the least possible. We shall prove firstly that  $n = 0$ . One can also assume that  $k \geq 2$ , otherwise, from (2.9),  $P_1(x) = 0$  and so  $n = -\infty$ . Take for instance  $k_1 \neq 0$ . If  $n > 0$ , let us differentiate the equality (2.9) with respect to  $x$ :

$$(2.10) \quad \sum_{i=1}^k (P_i' + r_i P_i) \exp(r_i x) = 0.$$

Since  $r_1 \neq 0$ , we can eliminate  $P_1 \exp(r_1 x)$  between (2.9) and (2.10) and obtain:

$$-\frac{1}{r_1} P_1' \exp(r_1 x) + \sum_{i=2}^k \left( P_i - \frac{1}{r_1} P_i' - \frac{r_i}{r_1} P_i \right) \exp(r_i x) = 0.$$

Here is an expression like that one from (2.9) but the sum of the degrees of the corresponding polynomials is at most  $n-1$ . Thus we just obtained a contradiction relative to the choice of  $n$ . Hence  $n = 0$ , i.e. any nontrivial linear combination between  $\exp(r_1 x), \exp(r_2 x), \dots, \exp(r_k x)$ ,

over  $K(x)$  must have coefficients in  $K$ . It remains to prove that from any linear combination

$$(2.11) \quad a_1 \exp(r_1 x) + a_2 \exp(r_2 x) + \dots + a_k \exp(r_k x) = 0,$$

one derives that  $a_1 = 0, a_2 = 0, \dots, a_k = 0$ . We prove this by mathematical induction on  $k$ . The statement is clear for  $k = 1$ . Suppose that the statement is true for  $k - 1$ . Let us prove it for  $k$ , i.e. we consider the equality (2.11). Let us differentiate (2.11):

$$(2.12) \quad r_1 a_1 \exp(r_1 x) + r_2 a_2 \exp(r_2 x) + \dots + r_k a_k \exp(r_k x) = 0.$$

Let us now multiply (2.11) by  $r_1$  and subtract the result from (2.12):

$$(r_2 - r_1) a_2 \exp(r_2 x) + \dots + (r_k - r_1) a_k \exp(r_k x) = 0.$$

By using the induction hypothesis we get:

$$(r_2 - r_1) a_2 = 0, \dots, (r_k - r_1) a_k = 0.$$

Since  $r_1, r_2, \dots, r_k$  are distinct, we conclude that  $a_2 = 0, a_3 = 0, \dots, a_k = 0$ . Coming back to (2.11) we find that  $a_1 = 0$  (we proved above that  $\exp(\lambda x) \neq 0$ ) and the proof of the lemma is completed.  $\square$

**Theorem 4.** *Let  $S$  be the  $K$ -vector subspace of  $\Omega$  which consists of all solutions  $y \in \Omega$  of the linear differential equation  $L[y] = 0$ . Then  $\dim_K S = n$ .*

*Proof.* Since for any  $i = 1, 2, \dots, k$  and for any polynomial  $P_i$  of degree  $t_i - 1$  one has  $L[P_i \exp(r_i x)] = 0$  (see Lemma 3) any element

$$y = \sum_{i=1}^k P_i \exp(r_i x) \in \Omega$$

is a solution of  $L[y] = 0$ . Since also  $\exp(r_1 x), \exp(r_2 x), \dots, \exp(r_k x)$  are linear independent over  $K(x)$ , we conclude that  $\{x^{j_i} \exp(r_i x)\}$ ,  $i = 1, 2, \dots, k$  and  $j_i = 0, 1, \dots, t_i - 1$  are linear independent solutions of  $L[y] = 0$ , over  $K$ . Thus  $\dim_K S \geq n = \sum_{i=1}^k t_i$ . But, from Remark 1,  $\dim_K S \leq n$  and thus  $\dim_K S = n$ .  $\square$

**Example 1.** Let  $K = \overline{\mathbb{Q}_3}$  be a fixed algebraic closure (see [LS]) of the 3-adic number field  $\mathbb{Q}_3$  (see [GP] or [G] for definitions and notation) and let

$$(2.13) \quad y'' + 2y = 0$$

be a linear differential equation of order two. If we search for a solution  $y \in K[[x]]$  like in Theorem 1, we can easily find two linear independent (over  $K$ ) power series  $y_1, y_2 \in \mathbb{Q}[[x]]$ , solutions of (2.13), such that the  $K$ -vector space of all solutions in  $K[[x]]$  of (2.13) can be generated



by  $y_1$  and  $y_2$ . Usually, it is not so comfortable to work with solutions in this form. The best idea is to search for solutions of the form:  $y^* = \exp(\lambda x) \in \Omega$ ,  $\lambda \in K$ . Since  $(y^*)' + 2y^* = 0$  implies  $\lambda^2 + 2 = 0$ , this means that  $\lambda = \pm i\sqrt{2}$ , where  $i = \sqrt{-1}$ ,  $\sqrt{2}$  are in  $K$ . They, separately, are not in  $\mathbb{Q}_3$ , but  $\pm i\sqrt{2} \in \mathbb{Q}_3$  (see [GP] or [G]), because the algebraic equation  $\lambda^2 + 2 = 0$  has two distinct solutions  $(\pm\hat{1})$  modulo 3. Thus,  $y_1^* = \exp(i\sqrt{2})$  and  $y_2^* = \exp(-i\sqrt{2})$  are linear independent solutions of (2.13) which generate the whole  $K$ -vector space of all solutions, i.e. any solution  $y$  is of the form:

$$y = C_1 y_1^* + C_2 y_2^*,$$

where  $C_1, C_2$  are arbitrary elements in  $K$ . This last description is easier than that one given in language of power series.

**Example 2.** Let this time  $K = \overline{\mathbb{C}(X)}$  be a fixed algebraic closure of the field  $\mathbb{C}(X)$  of rational functions with coefficients in the field of complex numbers. Let us consider the linear differential equation

$$y'' + Xy = 0,$$

with coefficients in  $K$ . It is very easy to find two linear independent power series  $y_1, y_2 \in \mathbb{Q}(X)[[x]]$  which generate the 2-dimensional vector space of all solutions of the differential equation, viewed in  $K[[x]]$ . However, by using the above theory, we can find two linear independent solutions  $y_1^* = \exp(\sqrt{X} \cdot x)$ ,  $y_2^* = \exp(-\sqrt{X} \cdot x)$  which can generate the same 2-dimensional vector space of all solutions, but in an easier way. Here  $\sqrt{X}, -\sqrt{X} \in K$  because of the Newton-Puisseux theorem ( $K = \cup_{n=1}^{\infty} \mathbb{C}((X^{\frac{1}{n}}))$ ), [Ab].

The above easy, elementary and elegant treatment of the linear differential equations with constant coefficients can be used for  $K = \mathbb{C}$ . An alternate treatment in this case one can find in [RR].

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